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**FACULTY OF ENGINEERING**

**DEPARTMENT OF COMPUTER ENGINEERING**

**COMP4910 Senior Design Project 1, Fall 2019**

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**POF: Performance Optimized Fluid System**

**Final Report**

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# PLAGIARISM STATEMENT

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# 

# KEYWORDS

|  |  |
| --- | --- |
| **Term** | **Description** |
| **Cell** | Axis aligned bounding box is divided into small identical cubes. |
| **Color field quantity** | It is a functionthat calculates how each particle is affected by all the other particles. |
| **Gradient** | The directional derivative of a scalar field gives a vector field directed towards where the increment is most, and its magnitude is equal to the greatest value of the change. |
| **Grid** | Series of vertical and horizontal lines that are used to subdivide AABB vertically and horizontally into cells in three-dimensional space. |
| **Iso-surface** | An isosurface is a 3D surface representation of points with equal values in a 3D data distribution which is the 3D equivalent of a contour line. |
| **Marching Cubes** | Marching cubes is a computer graphics algorithm, published in 1987 for extracting a polygonal mesh of an isosurface from a three-dimensional discrete scalar field. |
| **NVIDIA Flex** | NVIDIA Flex is a particle-based simulation technique for real-time visual effects. |
| **Polygonal Mesh** | A polygon mesh is the collection of vertices, edges, and faces that make up a 3D object. |
| **Unity 3D** | Unity is a cross-platform game engine developed by Unity Technologies. Unity is used for developing video games and simulations for consoles and mobile devices. |
| **Visual Studio** | Microsoft Visual Studio is an integrated development environment (IDE) from Microsoft. |

**Table 1:** Keywords

# ABSTRACT

The POF system aims to provide surface identification and visualization in particle-based liquid simulations more efficiently and quickly. Firstly, the necessary algorithms for the system have been determined as a result of the researches and these algorithms have been understood to be brought together. Secondly, the System is divided into several algorithms and a structure with a main control panel that manages these algorithms. These infrastructures provide memory efficiency (Spatial hashing) while gaining faster access to data, respectively. Surface recognition and surface recognition (marching cubes). As the project is research-based, it is possible that the structures we have described will change and different structures will be replaced. Therefore, these algorithms and structures may change in the future.

# ÖZET

POF sistemi parçacık temelli sıvı simülasyonlarında yüzey tanımlamasını ve görselleştirmesini daha optimize ve hızlı bir şekilde sunmayı amaçlar. İlk olarak Yapılan araştırmalar sonucunda sistem için gerekli algoritmalar belirlenmiş ve bu algoritmaların bir araya getirilmek üzere anlaşılması sağlanmıştır. İkinci olarak Sistem çeşitli algoritmalar ve bu algoritmaları yöneten ana bir kontrol paneline (controller) sahip bir yapıya bölünmüştür. Bu alt yapılar sırasıyla verilere daha hızlı erişim kazanırken hafıza verimliliği sağlar (Spatial hashing). Yüzeyin tanımlanması ve görselleştirilecek alanların belirlenmesi (Surface recognition) ve görselleştirmedir (Marching cubes). Projenin araştırma temelli olmasından dolayı anlattığımız yapıların değişmesi ve yerlerine daha farklı yapıların gelmesi muhtemeldir. Bu yüzden ilerleyen zamanlarda bu algoritmalar ve yapılar değişebilir.

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# LIST OF ACRONYMS/ABBREVIATIONS

|  |  |
| --- | --- |
| **AABB** | Axis Aligned Bounding Box. Bounding volume for a set of objects is a closed volume that completely contains the union of the objects in the set. |
| **API** | Application Programming Interface. |
| **CPU** | Central Processing Unit. |
| **GPU** | Graphic Processing Unit. |
| **OPENGL** | Open Graphics Library is a cross-language, cross-platform application programming interface for rendering 2D and 3D vector graphics. |
| **POF** | Performance Optimized Fluid |
| **SSF** | Screen Space Fluids Pro |

**Table 3:** List of acronyms/abbreviations

# 1. INTRODUCTION

This section gives main points about problem description, project goal and project output.

# 1.1. Description of the Problem

The main problem of the particle-based fluid simulation system is excessive numbers of the particles. There are millions of particles in a small number of liquids such as water. A particle is a rigid body sphere. Simulation applies physics to particles and these particles act as a liquid. Simulation having difficulties in calculations predicated on a surplus of particles. Indirectly, time and memory complexity increasing.

# 1.2. Project Goal

The main goal of the project researches whether there is a way to enhance fluid simulation. Increasing the efficiency and performance of an existing particle-based fluid simulation is a major goal. We aim to achieve these goals by implementing a variety of methods to the POF system such as using special structures to find store particles and visualize it by using various methods like the Marching cubes. In our project, there is no certain way because it is a research and development project and new more effective ways can be found during the project. Various methods and techniques will be researched and implemented while the project is in the development process.

# 1.3. Project Output

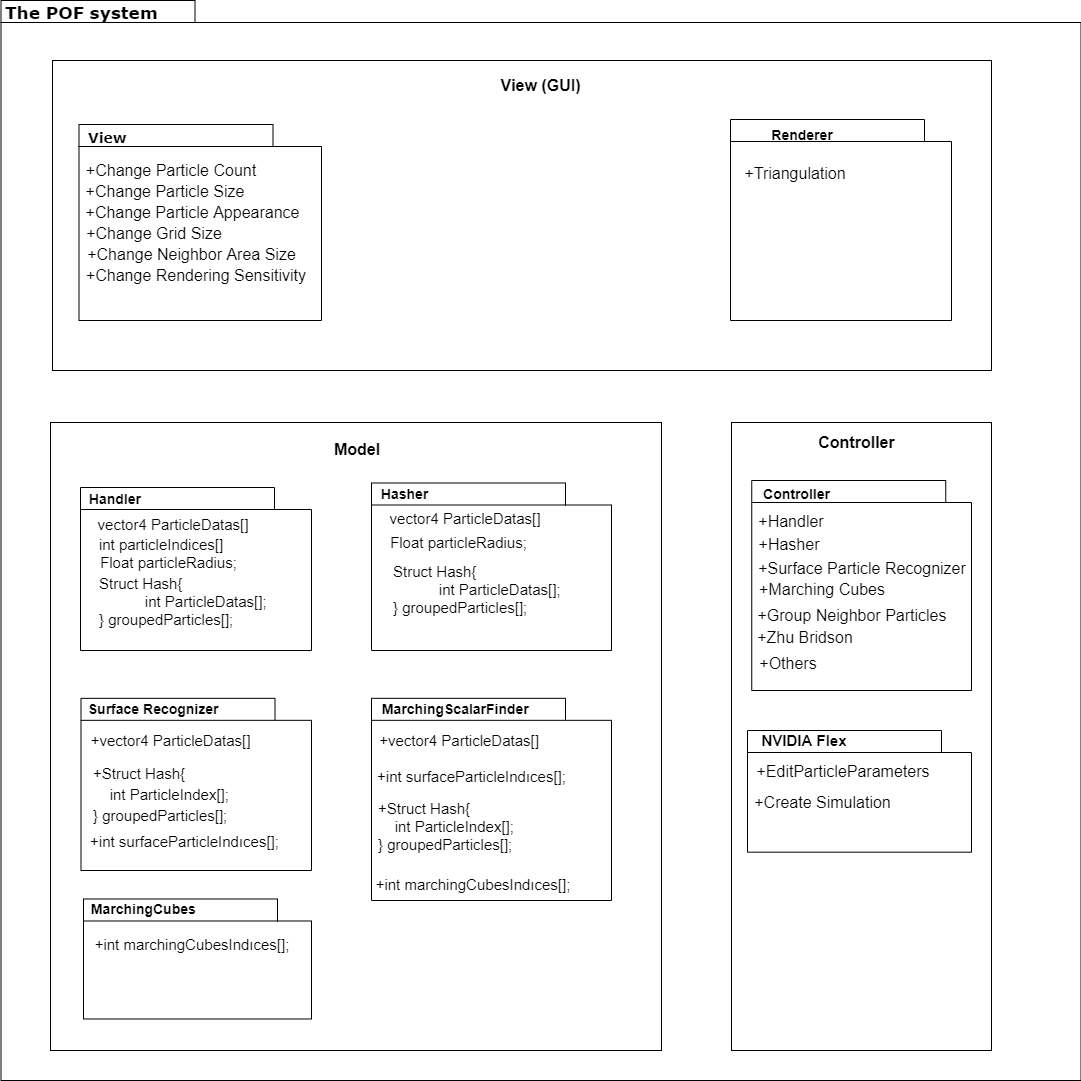
* Better performance.
* Better memory efficiency.
* Fluid-like appearance and behaviour.
* Testing of different algorithms for performance and efficiency.
* Higher frame rates per second.

# 2. DESIGN

This section describes about design of the POF system. High level and detailed designs are explained. Restrictions and conditions mentioned in this section.

# 2.1. High Level Design

**2.1.1 Package Diagram**



**Fig 1:** Package Diagram

Package diagram explains classes and their attributes along with relations. NIVIDA flex and Handler classes are the main parts of the system. Handler communicates to transmit data to relevant classes.

This section is extensively explained in design specification document [3] and it will be elaborated in future.

# 2.2. Detailed Design

Detailed design part is mentioned in design specification document. In DSD, [3] detailed design is explained with activity diagrams of the POF system. This section will be elaborated in future works.

# 2.3. Realistic Restrictions and Conditions in the Design

We had to neglect some aspects of the project to implement the project in a year. The security issue is ignored because the project aims to help everybody who has interested fluid simulations and contribute to science. We assumed that users of the POF system have the necessary equipment and software and know to how to use them.

# 3. IMPLEMENTATION and TESTS

This section describes implementation stages of the POF system. Code parts are given

# 3.1. Implementation of the System

**3.1.1. Research Papers and System Structure**

This project based on these two research papers, surface reconstruction algorithm that implemented by Zhu et al **[ZB05]** and Marching cubes algorithm **[WH87]**. However, some problems occurs when system structure creation stage is started on visualization. Our main problem was performance and memory efficiency on that point, we added two algorithm to our project for passing over on performance and memory issues.

**Main Problem Solution of Problem**

|  |  |
| --- | --- |
| Searching particle data linearly due to 3D space positions and vector3 to integer translation. | Spatial hashing algorithm provides reaching particles by put them into cell data. |
| Too many particle appears in simulations and handling all of them occurs performance problems. | Do not put into calculations inactive and unnecessary particle on visualization (surface particle finding algorithm). |

After these solutions, we have started implement our system structure by creating classes but we realize complexity getting higher due to interconnection between classes, so we create a handler class for control every classes in the one class.

**3.1.2 Implementation of Hash algorithm**

We use spatial hash algorithm to access particle position easily. Hash algorithm simplifies the three dimensions of float particle positions to integer id numbers in specific order.

Cube numbering is starts from top left and from left to right and then top to bottom. Then it implies the same operation for the third dimension. On x dimension, we found cell id by subtract minimum boundary area x from particle x so it means that numbering increases from left to right. Same logic implies on y dimension, cell id number increase from top to bottom and similarly cell id number increases from backward to forward in z dimension.



**Fig 1:** cell id numbering

We can reach cell id by position without storing it.



**Fig 2:** Group struct



**Fig 3:** Hash size

Vertex index struct represents cells by creating an array on this struct. We created cell ids as indices. By finding how many grids in each dimension we find our hash table size represented as fig.3. . We find particles by looking cells. Each cell represented by integer id number as seen in fig.2.

We have realized during the implementation when particle center on intersection point of cell boundaries. We solve this problem by calculating subtract particle x/y/z from boundary max x/max y/max z and divide our grid size. If the remainder is equals to zero is on the boundary.



**Fig 4:** Intersection boundaries check.

For example in fig. 4. we found that particle on intersection boundaries and we found its second cell on y dimension

So that way we can find the particles by looking in cells instead of linear search of the particles. Ceiling is implemented to derive integer numbers because particles are float and they are derived according to the AABB size.

**3.1.3 Particle neighbor algorithm**

**Yüzey particle algoritmalarına geçtiğimiz zaman bir part etrafındaki belirli bir uzaklıktaki komşuların ona olan etkisini bulmalıyız. Matematiksel işlem ve tutatlılık için arayacağımız hacim küresel şekilde olmalıydı fakat bu algoritmanın araştırılması için gereken zaman ve yogunluk dolayısıyla daha hızlı olan arayacagımız hacimi küp olarak belirledik. Komşu part ları bulabilmemiz için arayacagımız hacmin içindeki hashlediğimiz cellleri id olarak bulmak lazım. Bunu da rahatça bir şekilde çözebilmek için toplam 3 tane köşe celline ihtiyacımız oldu: bu üç cellden tx, ty ve tz olmak üzere cellerin her boyuttaki toplam ilerlediği grid aralıklarını buluyoruz böylece alanın içinde kalan bütün celleri tek bir cellden yola çıkarak bulup, komşu particleları grupladığımız cellerden bulmuş oluyoruz.**

**//. komsu particle ları bulmak için**

This project is not completely finished. Therefore this section will be completed in future works.

# 3.2. Tests and Results of Tests

**3.2.1 Availability of the Necessary environment**

Before finding NVIDIA Flex, we have tested three particle based fluid simulation and we disqualify for these reasons;

|  |  |
| --- | --- |
| **uFlex** | Had small bugs and errors in the code, even though we have fixed minor bugs, the particles were not recognizing the collider of the objects. Collider of the simple primitive objects was not recognized by the Uflex and particles were penetrating the objects. The only plane object was being recognized by the uFlex. The problem could not be solved, and we have changed the fluid simulation. |
| **Obifluid** | Obifluid is eliminated because of performance problems. The expected result was not satisfied by the Obifluid compared to other fluid simulations our expectation was reaching 30fps with a hundred thousand particle but in three thousand particles we have 3fps. |
| **Screen Space Fluids Pro** | Like uFlex we recognize small bugs and errors in the code and we fixed it but performance was very low on higher particle count. |

# 4. CONCLUSIONS

In this section, the cost table of workers is given and explained. The cost of software and hardware is given with details and benefits of the projects are explained. This part of the final report summarizes our project and gives a cost analysis for the project. Future works mentioned.

# 4.1. Summary

The massive amounts of particles can be a computational hardship for the computer.

We implement various methods to get better results by making a research. Our project focuses on catalyzing computational difficulties by increasing the performance and efficiency. Project should make easier to simulate with higher quantities of particles or getting better results with the same number of particles.

# 4.2. Cost Analysis Table

**4.2.1 Cost of workers**

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| **Members** | **Day/Hour** | **Week/Hour** | **Semester/Hour** | **Salary/Hour** | **Salary/Monthly** | **TOTAL** |
| Member | 8 | 40 | 560 | 30 TL | 4800 TL | 16800 TL |

**Table 4:** Cost Analysis of Workers

As shown in the cost analysis table, three people works in the project. Every people work equally as workload. Therefore, only one member is represented on the cost table.

Every member works 8 hours a day and 5 days a week. A semester consists of 14 weeks and salary is 30 Turkish lira per hour. Each member costs 4800 TL per month and costs 16800 in a semester. The salary costs of all three members are 50400 TL per semester. The equivalent of 16800 TL is $2894, 67. Currency translation has made from Dollar / Turkish Lira = 1 / 5.80 in 10 December 2019.

**4.2.2 Cost of Software**

|  |  |
| --- | --- |
| **Title of Software** | **Cost** |
| uFlex | $30 |
| Obi Fluid | $30 |
| SSF | $7 |
| **Total Cost** | **$67** |

**4.2.3 Cost of Hardware**

Total cost = Total employee cost + Total software cost + Total Hardware cost (PC1)

|  |  |
| --- | --- |
| **PC 1 components that used in Project** | **Description** |
| Operating System | Windows 10 (64-bit) |
| Processor | Intel Core i7-4700 HQ CPU |
| Memory | 16 GB RAM – DDR3L-1600 MHz |
| GPU | NVIDIA GeForce GTX850M 4GB DDR3 |
| Cost of PC 1 per user | $1693, 21 |
| **Total cost (for 1 worker)** | **$4684, 88** |
| **Total cost (for 3 workers)** | **$14054, 64** |

**4.2.3.2 Optimal Simulation Computer (PC 2)**

Total cost = Total employee cost + Total software cost + Total Hardware cost (PC2)

|  |  |
| --- | --- |
| **Optimal Simulation Computer (PC 2)** | **Description** |
| Operating System | Windows 10(64-bit Pro) |
| Processor | 8-core Intel i7 5.1 GHz |
| Memory | 32 GB RAM- DDR4- 2666MHz |
| GPU | NVIDIA Quadro P2200 5GB |
| Cost of PC 2 per user: | $5017 |
| **Total cost (for 1 worker)** | **$8008,67** |
| **Total cost (for 3 workers)** | **$24026,01** |

# 4.3. Benefits of the Project

Our project can benefit in all areas where liquid simulation is available.

**4.3.1 Animations and Movies:** The POF system can be used in any movies, animations that used fluids.

**4.3.2 Scientific work:** Our project benefit scientific areas the most because the project is heavily research and development based of the research papers about the particle-based fluid simulations. Scientist and researchers can use the POF system for their scientific researches

**4.3.3 Games:** Some games need a fluid simulation system to make more realistic games. The POF system can be a good factor for the makes realistic games. For instance, in sailing simulator game is a perfect match for our system.

**4.3.4 Construction:** The construction and Architecture sector can benefit from our system because the simulation is physics-based which means the POF system is almost realistic. The POF system neglects some imperceptible elastic deformations. For instance, a civil engineer can build a barrage and want to test endurance, on the computer simulation. Therefore, our system can be used for construction and architecture testing.

# 4.4. Future Work

We will develop our project in order to achieve performance and efficiency goals. The functionality of the project will remain the same. However, small changes in the calculations will be changed to get better results.

# References

1. Requirement Specification Document revision 1.0 (RSD 1.0)
2. Requirement Specification Document revision 2.0 (RSD 2.0)
3. Design Specification Document revision 1.0 (DSD 1.0)